

KARTIKEYA BECTOR

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EDUCATION

Columbia University

New York, NY

M.S. Mechanical Engineering (Robotics and Control Track), GPA: 3.62/4.00

Sep 2021 – (exp) Dec 2022

Coursework: Robot Learning, Human-Centered Design and Innovation, Mechatronics and Embedded Microcomputer Control, Robotics Studio, Introduction to Robotics, Data Science for Mechanical Systems, Evolutionary Algorithms

Delhi Technological University (DTU)

Delhi, IN

B. Tech (Mechanical Engineering), GPA: 7.70/10.00

Aug 2017 - Jul 2021

Coursework: Mechanics of Solids, Manufacturing Tech., Adv. Manufacturing Processes, Production and Operations Management
Awards: Research Excellence Award for contributing to 10 research papers over 2 years in advanced manufacturing and composites

EXPERIENCE

Vimaan Robotics, Inc.

Santa Clara, CA

Mechatronics Intern (R&D Department)

Jun 2022 – Aug 2022

- Designed complex assemblies, proprietary components and adapters on SOLIDWORKS with GD&T – 3D printed for deployment
- Built electromechanical experimental setups, using 80/20s, 3D-printed and laser-cut parts, to determine lighting requirements in machine vision applications – wrote Arduino scripts to control the various components
- Developed Python simulation and lighting visualization program to test setup configurations for optimal camera exposure based on application – reduced testing time from 1 day to a few minutes; conceptualized in-house solution, cost reduced by 50%
- Automated data collection processes by writing OpenCV-python and v4l2-ctl script, increasing efficiency by 90% - also processed readability of collected data using Google API

Robotics and Rehabilitation Laboratory (ROAR)

New York, NY

Graduate Research Assistant (mTPAD Project)

Jan 2022 – May 2022

- Worked with mTPAD (mobile Tethered Pelvic Assist Device) – applies corrective lateral and diagonal forces to help improve irregular gait patterns of stroke patients with hemiplegia
- Created virtual environment on Unity (using C#) to do exergaming (exercise gaming) therapy
- Integrated HTC Vive (VR) with mTPAD for assistive feedback during exergaming for more effective physical therapy

Columbia University Robotics Club

New York, NY

Analysis Team Lead (NASA Big Ideas 2022: Extreme Terrain Mobility Challenge)

Nov 2021 – May 2022

- Supervised team of 5 undergrad and grad students to devise alternative rover locomotion modalities to traverse lunar craters (with slopes > 35°) and lava tubes in extreme thermal and lunar terrain applications (and later, Mars)
- Simulated and trained 16-parameter locomotion model on self-programmed physics simulator on Python (using VPython) by forming evolutionary algorithms to optimize gait and evolve gait-modulation for damage scenarios
- Designed and manufactured working demonstration of final micro-spine gripper

PROJECTS

Laika – The Dancing Robot Dog | Columbia University

New York, NY

Robotics Studio

Sep 2021 – Dec 2021

- Ideated, designed and manufactured dancing robot dog over the course of 12-weeks
- Created detailed CAD model on SOLIDWORKS and Fusion 360; fabricated body components using 3D printing and laser cutting
- Configured remotely controllable system to communicate with on-board RaspberryPi using SSH over Wi-Fi
- Programmed gait of robot using Keyframes method for 8 servo motors for robot to have 4 distinct dance moves. Presently teaching robot to walk on its own using PyBullet simulations and evolutionary algorithms

TECHNICAL SKILLS

- Languages and Libraries: MATLAB, Python, OpenCV, VPython, PyBullet, Pandas, PyGAD, C#, Unity, MiniTab, Linux
- Design: SOLIDWORKS, Fusion 360
- Mechanical: MFSP, 3D Printing, Laser Cutting, CAM, Milling, Turning

LEADERSHIP EXPERIENCE

International Conference on Advanced Production and Industrial Engineering

Delhi, IN

Organizing Coordinator

Aug 2019 - Jun 2021

- Managed cross-functional team of 50+ students in 6 locations pan-India to organize international conference (hybrid mode), attended by 1000+ delegates globally
- Executed digital and referral marketing strategy to increase reach of event to 15 colleges and 5K+ research scholars worldwide, resulting in 200% (\$60K) increase in revenue